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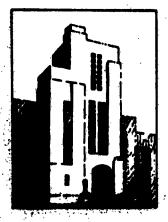
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A METHOD FOR THE CALCULATION OF THE TURBULENT BOUNDARY LAYER IN A PRESSURE GRADIENT

by

Paul S. Granville



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NOTATION

- A Coefficient in general auxiliary equation, Equation [84]
- a Constant in Equation [19]
- B Coefficient in general auxiliary equation, Equation [84]
- b Constant in Equation [19]
- C Constant
- C_f Drag coefficient, $D/\frac{1}{2}\rho U^2 S$
- D Drag
- E Function of H in Table 3
- e Base of natural logarithms
- H Shape parameter of velocity profiles, δ^*/θ
- I Shearing-stress distribution integral, $\int_0^1 \frac{\tau}{\tau_w} d\left(\frac{y}{h}\right)$
- i Subscript referring to initial conditions
- n Exponent of power law for velocity profiles, Equation [8]
- o Subscript for flat-plate quantities
- p Pressure in fluid
- q Exponent in Equation [62]
- R_x Reynolds number based on x, η_x/ν
- R_a Reynolds number based on θ , $U\theta/\nu$
- r. Transverse radius to surface of body of revolution
- S Surface area
- s Constant in Equation [26]
- t Subscript indicating quantities at the trailing edge of an airfoil
- U Velocity at outer edge of boundary layer
- U_ Undisturbed velocity of fluid
- u Velocity in boundary layer parallel to surface
- u_{\perp} Friction velocity, $\sqrt{\tau_w/\rho}$
- v Velocity in boundary layer normal to surface
- W Width
- x Coordinate parallel to surface
- y Coordinate normal to surface
- α Pressure-gradient parameter, $\frac{\delta}{\tau_{u}} \frac{dp}{dx}$
- eta Shearing-stress parameter, $rac{ au_{w_i}}{ au_w} rac{\delta}{\delta_i}$
- Buri pressure-gradient parameter, $\frac{\theta}{U} \frac{dU}{dx} R_{\phi}^{1/4}$

- γ Velocity parameter, $\left(\frac{u}{U}\right)_{y=0}$
- 5 Thickness of boundary layer
- δ^* Displacement thickness of boundary layer, $\int_0^{\delta} \left(1 \frac{u}{U}\right) dy$
- ¿ Buri skin-friction parameter
- η Gruschwitz velocity profile shape parameter, 1 γ^2
- 6 Momentum thickness of boundary layer, $\int_0^t \frac{u}{U} \left(1 \frac{u}{U}\right) dy$
- ν Kinematic viscosity of fluid
- ρ Density of fluid
- au Shearing stress
- Two Shearing stress at wall
- Parameter for integral of shearing-stress

distribution, $\int_0^{\delta/\delta^+} \frac{\tau}{\rho U^2} d\left(\frac{y}{\delta^+}\right)$

A METHOD FOR THE CALCULATION OF THE TURBULENT BOUNDARY LAYER IN A PRESSURE GRADIENT

bу

Paul S. Granville

ABSTRACT

A method is described for the calculation of the development of incompressible turbulent boundary layers in pressure gradients, so that drag and separation of flow may be predicted more accurately. The principal contribution is the formulation of new relations for the variation with pressure gradient of 1, the shearing stress at the wall (local skin friction) and of 2, the integral of the shearing stresses across the boundary layer for use in a moment-of-momentum equation recently derived by Tetervin and Lin.

With the assumption of the one-parameter characterization of velocity profiles by a shape parameter H, the moment-of-momentum equation and the von Karman momentum equation constitute a working method involving the solution of a pair of simultaneous first-order differential equations.

As an introduction to the subject of turbulent boundary layers in pressure gradients, a review of previous methods is included in this report.

INTRODUCTION

An accurate calculation of the growth of turbulent boundary layers in a pressure gradient is required for many problems in hydrodynamics, aerodynamics and hydraulics where high Reynolds numbers are involved. Some of these problems are the calculation of the drag of airfoils and of bodies of revolution, the prediction of separation of flow on airfoils, the prediction of flow conditions in the test sections and diffusers of water tunnels and wind tunnels, and the prediction of the flow (frictional wake) around the tails of bodies of revolution for use in designing propellers and control surfaces.

Unlike laminar boundary layers, turbulent boundary layers are not very amenable to mathematical analysis owing to the present incomplete state of knowledge of the mechanics of turbulent flow. Nevertheless, considerable success in analyzing turbulent boundary layers on flat plates with zero pres-

sure gradient has been achieved by such investigators as Prandtl and von Kármán. No comparable progress has been attained to date, however, in the theory of turbulent boundary layers in a pressure gradient, especially in an adverse (positive) pressure gradient.

Briefly, the current objective for analyzing turbulent boundary layers in a pressure gradient is to develop an equation for the variation of the shape of the velocity profile within the boundary layer. This formulation is required as an auxiliary equation for complementing the well-known von Karman momentum equation. Auxiliary equations have been obtained empirically by a number of investigators. Because of significant differences existing among these empirical formulations, Tetervin and Lin attempted a theoretical approach to the problem. One of the equations obtained by them is a moment-of-momentum equation derived from the basic Prandtl boundary-layer equations and from a one-parameter characterization for the shape of the velocity profiles. Although the moment-of-momentum equation of Tetervin and Lin has the required form for an auxiliary equation, it lacks essential relations needed for numerical computations-namely, the variation with pressure gradient of the shearing stress at the surface (local skin friction) and of the integral of the distribution of the shearing stresses across the boundary layer. The principal aim of this paper is to supply the necessary shearingstress relations to this moment-of-momentum equation in order to develop a suitable auxiliary equation with a theoretical basis, to be used in conjunction with the von Karman momentum equation.

The relation for the local skin friction in a pressure gradient is derived on the basis of the recent work of Ludwieg and Tillmann who demonstrated the validity of applying the so-called "law of the wall" to the inner flow in the boundary layer. The integral of the transverse distribution of the shearing stresses in a pressure gradient is found empirically in this paper to be a function of similar flat-plate data for zero pressure gradient.

The moment-of-momentum equation, after being modified by the inclusion of the shearing-stress relations, is demonstrated to agree with the average of other existing auxiliary equations whose formulation is based on purely empirical grounds.

FUNDAMENTAL RELATIONS FOR TURBULENT BOUNDARY LAYERS

Some of the fundamentals of turbulent boundary layers are briefly reviewed here as an introduction to the subject. The comprehensive summaries by Prandtl, Goldstein, and Schlichting, References 1, 2, and 3 respectively, should be referred to for fuller details.*

^{*}References are listed on page 38.

In general, steady fluid flow (quasi-steady for turbulent flow) manifests itself in two distinct types of motion, laminar at low Reynolds numbers and turbulent at high Reynolds numbers. Whereas laminar flow proceeds in a regular pattern of streamlines, turbulent flow advances in a haphazard combination of mixing motions. Although the variations in velocity and pressure of turbulent flow follow a random course, they may be considered to fluctuate about some mean value as shown in Figure 1.

The analytic treatment of turbulent flow consists in separating the fluid motion into a mean flow and a superposed fluctuation flow. Then the

mean and fluctuation velocities and pressures are substituted into the Navier-Stokes equations for viscous flow and into the equation of continuity. After appropriate time averages are formed, the resulting equations in terms of mean quantities resemble those for laminar flow, with the exception of additional terms involving averages of various products of the fluctuation quantities. These fluctuation terms represent the mixing motion of turbulence and act as apparent stresses (Reynolds stresses) within the fluid. Since an analytical description of the Reynolds stresses has not been formulated, a direct solution of the differential equations for turbulent flow is virtually impossible.

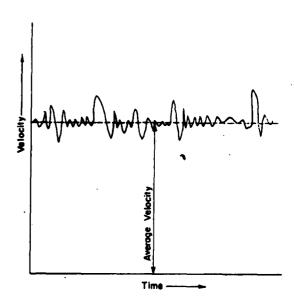


Figure 1 - Velocity Fluctuations of Turbulent Flow at a Fixed Position

The theory of the flow of viscous fluids serves as a useful guide, however, even though empirical or semi-empirical methods may be followed in many practical cases.

At relatively high Reynolds numbers, the viscous effects of fluids like air or water are confined mostly to a narrow region or band next to the solid surface. The laminar flow through this region, or boundary layer as it is better known, acts in the same manner as fully developed viscous flow in pipes, inasmuch as it becomes turbulent after a critical value of some Reynolds number is exceeded. The equations of motion for the turbulent boundary layer are found analytically from the Navier-Stokes equations for turbulent flow in a way analogous to that for the laminar boundary layer—that is, by

rejecting terms involving small orders of magnitude. For steady incompressible flow with negligible longitudinal curvature, the turbulent-boundary-layer equations of motion are found to be

$$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} = -\frac{1}{\rho}\frac{\partial p}{\partial x} + \frac{1}{\rho}\frac{\partial \tau}{\partial y} ; \frac{\partial p}{\partial y} = 0$$
 [1]

for $0 \le y \le \delta$ and $0 \le u \le U$. Here u and v are the x- and y-components of the velocity within the boundary layer, parallel and normal to the surface of the body respectively, U is the velocity at the outer edge of the boundary layer, δ is the thickness of the boundary layer, ρ is the density of the fluid, and τ is the total shearing stress within the fluid. It is to be noted that the velocities and pressures indicated in Equation [1] represent time averages of the turbulent quantities in the flow. In addition to two-dimensional flow, Equation [1] is also applicable to axisymmetric flow when the boundary-layer thickness δ is small relative to the transverse radius of the solid boundary r_w

The accompanying equation of continuity for two-dimensional flow is

$$\frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \frac{\partial \mathbf{v}}{\partial \mathbf{y}} = 0$$
 [2a]

and for axisymmetric flow it is

$$\frac{\partial \mathbf{u}}{\partial \mathbf{x}} + \frac{\partial \mathbf{v}}{\partial \mathbf{y}} + \frac{\mathbf{u}}{\mathbf{r}_{\mathbf{w}}} \frac{\partial \mathbf{r}_{\mathbf{w}}}{\partial \mathbf{x}} = 0$$
 [2b]

for \$ << rw.

From the boundary-layer equation of motion, Equation [1], and the equation of continuity, Equation [2], the von Kármán momentum equation is derived by integrating each term of [1] with respect to the y-coordinate. The von Kármán equation represents the basic working equation for calculating the growth of boundary layers in the presence of pressure gradients. For purposes of analysis the momentum equation is best expressed in terms of the displacement thickness δ^* , the momentum thickness θ and the shape parameter H which are defined as

$$\delta^* = \int_0^{\delta} \left(1 - \frac{u}{U}\right) dy$$
 [3]

$$\theta = \int_0^{\theta} \frac{u}{U} \left(1 - \frac{u}{U} \right) dy$$
 [4]

and

$$H = \frac{\delta^+}{\theta}$$
 [5]

In terms of these quantities the von Karmán momentum equation for twodimensional flow becomes

$$\frac{d\theta}{dx} + (H + 2) \frac{\theta}{U} \frac{dU}{dx} = \frac{\tau_W}{\rho U^2}$$
 [6a]

and for axisymmetric flow it becomes for $\delta \ll r_{\omega}$

$$\frac{d(\mathbf{r}_{\mathbf{W}}\theta)}{d\mathbf{x}} + (\mathbf{H} + 2) \frac{\mathbf{r}_{\mathbf{W}}\theta}{\mathbf{U}} \frac{d\mathbf{U}}{d\mathbf{x}} = \mathbf{r}_{\mathbf{W}} \frac{\tau_{\mathbf{W}}}{a\mathbf{U}^{2}}$$
 [6b]

where τ_{\bullet} is the shearing stress at the wall.

Physically the von Kármán momentum equation is interpreted as representing the rate of change of the momentum of the fluid within the boundary layer as a function of the frictional resistance and of the pressure gradient. When solving a particular problem, U, the velocity at the outer edge of the boundary layer, and dU/dx, representing the pressure gradient, are given by measurements from pressure taps on the body or by potential-flow calculations. Quantities such as the shape parameter H and the local-skin-friction coefficient $\tau_{\rm w}/\rho{\rm U}^2$, have to be determined by other means. By assuming flat-plate values for H and $\tau_{\rm w}/\rho{\rm U}^2$, the momentum equation can be integrated to give an approximate solution which in many cases is not adequate for the problem in question. The more exact solution depends on acquiring auxiliary relations for the variation of H and $\tau_{\rm w}/\rho{\rm U}^2$ in a pressure gradient. The detailed consideration of H and $\tau_{\rm w}/\rho{\rm U}^2$ in a pressure gradient is the major theme of this paper and will be discussed fully in the subsequent sections.

As an illustration of the flow idealized by boundary-layer theory, Figure 2 shows the flow pattern around a body of revolution. Essentially, there is potential flow outside the boundary layer and viscous flow within. The viscous boundary-layer flow is laminar from the nose up to the transition zone where it develops into a turbulent flow. Beyond the tail, the flow through the boundary layer merges to form a wake trailing behind the body.

The velocity U at the outer edge of the boundary layer is that of potential streamline and varies from zero at the stagnation point at the nose, through a range of values along the body to the free-stream velocity U_{∞} in the wake at infinity. Although the pressure p at the outer edge of the boundary layer is essentially the same as that across the boundary layer, it varies along the body with x and thus produces a pressure gradient. The pressure p and the velocity U of the potential streamline are related by the Bernoulli equation as follows

$$p + \frac{1}{2}\rho U^{2} = constant$$

$$\frac{dp}{dx} + \rho U \frac{dU}{dx} = 0$$
[7]

A negative pressure gradient is favorable and a positive pressure gradient adverse for preventing separation of flow.

or

Within the boundary layer the velocity u is zero at the surface, since no slippage occurs, and increases to U at the outer edge of the boundary layer. This variation of u with y, or the velocity profile, is very important in the study of boundary layers. In the case of turbulent boundary layers, the following power law variation gives an excellent approximation for most flow conditions, and a rough approximation for strong adverse pressure gradients.

$$\frac{u}{U} = \left(\frac{y}{\delta}\right)^n$$
 [8]

where the value of the exponent n depends on the previous development of flow in the boundary layer.

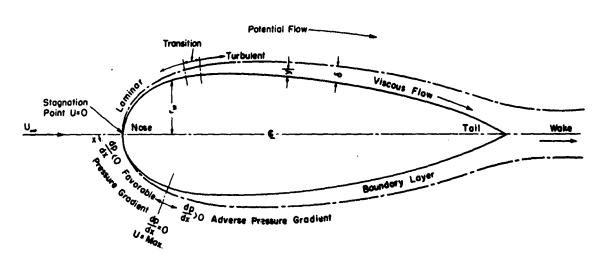


Figure 2 - Typical Boundary Layer Around a Body of Revolution

EXISTING METHODS FOR CALCULATING TURBULENT BOUNDARY LAYERS IN A PRESSURE GRADIENT

Interest in effects of pressure gradient on turbulent boundary layers has centered largely on adverse (positive) pressure gradients causing separation of flow such as occur in diverging conduits and on the suction side of airfoils at large angles of attack. (A review of the literature on this subject appears in Reference 4.) Since separation of flow is characterized by a reversal in the direction of flow at the surface, the velocity profile of the boundary layer suffers marked changes in shape as the flow approaches the point of separation, as seen in Figure 3. Hence the study of flow leading to separation must be directed towards the determination of the manner in which the shape of the velocity profile is affected by pressure gradients, as well as by other factors, such as Reynolds number.

Since a single parameter for the shape of the velocity profile greatly simplifies the mathematical analysis, considerable effort towards this goal has been expended by various investigators. Gruschwitz⁵ plotted u/U against y/θ in his experimental study of velocity profiles and, as shown in Figure 3, obtained a family of velocity profiles in various pressure gradients. He concluded that the value of u/U at some standard value of y/θ could be used to characterize the shape of the velocity profile for any pressure gradient. Following this concept Gruschwitz defined a form parameter η such that

$$\eta = 1 - \left(\frac{u}{U}\right)_{u=0}^{2} = 1 - \gamma^{2}$$
 [9]

where $\gamma = \left(\frac{u}{U}\right)_{u=0}$ Since the shape parameter H, which can be written

$$H = \int_{0}^{\theta/\theta} \left(1 - \frac{u}{U}\right) d\left(\frac{y}{\theta}\right)$$
 [10]

is also a function of the shape of the velocity profile, it cannot be independent of η if the single-parameter relationship holds.

This is confirmed by Gruschwitz who plotted H against η for a series of test data. As seen in Figure 4, a fairly smooth variation between η and H results. It is to be noted that Kehl, from tests covering a wider range of Reynolds numbers than Gruschwitz, found that η is not a unique function of H but that it varies slightly with Reynolds number.

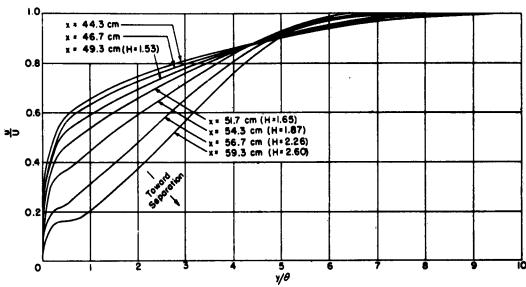
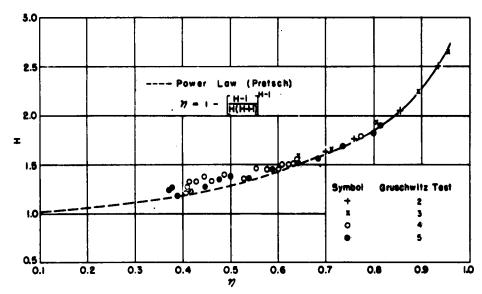


Figure 3 - Velocity Profiles of a Turbulent Boundary Layer In a Pressure Gradient (Gruschwitz, Reference 5)



では、これでは、10mmのでは、10mm

Figure 4 - Shape Parameter H as Function of Gruschwitz Form Parameter η (Schlichting, Reference 3)

Instead of η , von Doenhoff and Tetervin preferred the use of the shape parameter H itself as the single parameter to characterize the shape of the velocity profiles. Points from an extensive collection of test data were plotted together in the form

$$\frac{u}{U} = f\left(\frac{y}{\theta}, H\right)$$
 [11]

As seen in Figure 5, plots of u/U against H yield single curves for each value of y/θ .

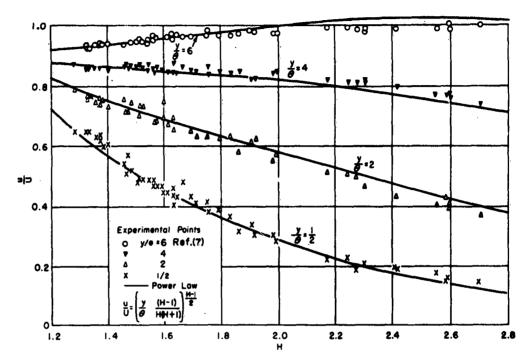


Figure 5 - Comparison of Power-Law Velocity Profiles with Experimental Points of von Doenhoff and Tetervin, Reference 7

For purposes of mathematical analysis it is found very useful to. consider a general-power-law distribution for the velocity profiles of the form

$$\frac{\mathbf{u}}{\mathbf{u}} = \left(\frac{\mathbf{y}}{\delta}\right)^n \tag{8}$$

Using this power law Pretsch⁸ derived the following relations between the boundary-layer parameters

$$\frac{\delta^{*}}{\delta} = \frac{n}{n+1} = \frac{H-1}{H+1}$$
 [12]

$$\frac{\theta}{\delta} = \frac{n}{(n+1)(2n+1)} = \frac{H-1}{H(H+1)}$$
 [13]

$$H = 2n + 1$$
 [14]

and finally

$$\eta = 1 - \left[\frac{H-1}{H(H+1)} \right]^{H-1}$$
 [15]

The curve for the relation just derived for $\eta(H)$ is drawn on Figure 4 and shows close agreement with the test data of Gruschwitz. Likewise the curve for the power law for the velocity profiles may be expressed in the form

$$\frac{\mathbf{u}}{\mathbf{U}} = \left[\left(\frac{\mathbf{y}}{\boldsymbol{\theta}} \right) \frac{\mathbf{H} - 1}{\mathbf{H}(\mathbf{H} + 1)} \right]^{\frac{H}{2}}$$
 [16]

Curves drawn from this equation in Figure 5 show close agreement with the data of von Doenhoff and Tetervin. From the experimental evidence just considered, it is seen that the general power law is an excellent approximation for the velocity profiles of turbulent boundary layers.

After the particular parameter for the shape of the velocity profile has been selected, its variation in a pressure gradient remains to be determined. It is now recognized that the rate of variation of this shape parameter and not the parameter itself is dependent upon the local-pressure-gradient parameter and upon other local parameters of the boundary layer. However, an early study by Buri⁹ in 1931 on accelerated and retarded flows in closed conduits considered the shape of the velocity profile to depend directly on the pressure gradient.

The parameter used by Buri for the shape of the velocity profile is

$$\Gamma = \frac{\theta}{U} \frac{dU}{dx} R_{\theta}^{1/4}$$
 [17]

where $R_{\rho} = \frac{U\theta}{\nu}$ and ν is the kinematic viscosity of the fluid. Actually Γ is a local parameter for the pressure gradient and hence can only roughly represent the shape of the velocity profile whose development depends on the previous history of the flow. The parameter Γ as used by Buri in his analysis has merit in providing a simplified method for calculating the momentum thickness θ approximately. When Γ is substituted into the von Kármán momentum equation, Equation [6a], the following expression is obtained

$$\frac{\mathrm{d}}{\mathrm{dx}}(R_{\theta}^{1/4} \theta) = \frac{5}{4} \left[\zeta - \Gamma \left(H + \frac{9}{5} \right) \right]$$
 [18]

where $\zeta = \frac{\tau_{\rm W}}{\rho \, {\rm U}^2} \, {\rm R}_{\rm e}^{1/4}$. From experimental evidence, Buri linearized this ex-expression to

$$\frac{\mathrm{d}}{\mathrm{d}x}(R_{\theta}^{1/4}\,\theta) = a - b\Gamma \tag{191}$$

$$\frac{d}{dx}(R_{\theta}^{1/4}\theta) = a - \frac{b}{U}\frac{dU}{dx}(R_{\theta}^{1/4}\theta)$$

where a and b are empirical constants. Equation [19] is integrated as a linear first-order equation in terms of $R_{\theta}^{1/4}\theta$ to provide a direct solution for the momentum thickness θ . From test data Buri considered separation to occur at $\Gamma = -0.06$. The Buri method of analysis was continued by Howarth¹⁰ who refined the method by solving Equation [18] directly, using experimental data for ζ and H.

At the same time that Buri published his work, Gruschwitz⁵ presented a more satisfactory method of analysis. Introducing the shape parameter η and realizing that its rate of change in a pressure gradient is more important than its local value, Gruschwitz plotted the nondimensional differential quantity $-\frac{\theta}{U^2}\frac{d}{dx}(U^2\eta)$ against η and obtained a linear variation for his test data as shown in Figure 6. Although Gruschwitz expected some effect due to Reynolds number, the narrow range of his data, 1 x 10³ < R_e < 4 x 10³, precluded any such indication and consequently he included no Reynolds number

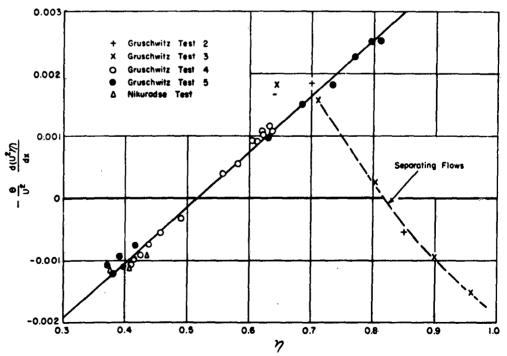


Figure 6 - Gruschwitz Form Parameter η as Function of Pressure Gradient (Gruschwitz, Reference 5)

effect in his analysis. The empirical equation fitting his test points is given as

$$-\frac{\theta}{U^2} \frac{d(U^2 \eta)}{dx} = 0.00894 \eta - 0.00461$$
 [20]

for $\eta < 0.8$. When $\frac{\theta}{U^2} \frac{d(U^2\eta)}{dx}$ is expanded to $\theta \frac{d\eta}{dx} + 2\eta \left(\frac{\theta}{U} \frac{dU}{dx}\right)$, it is seen that the rate of variation of η , $d\eta/dx$, and the nondimensional pressure gradient $\frac{\theta}{U} \frac{dU}{dx}$ are both included in Equation [20]. The variation of η is calculated from the auxiliary equation, [20], when used simultaneously with the von Kármán momentum equation. Gruschwitz considered separation to occur at $\eta \ge 0.8$ which is equivalent to $H \ge 1.85$.

From test data covering a wider range of Reynolds numbers, $1 \times 10^{5} < R_{e} < 3.5 \times 10^{4}$, Kehl⁶ incorporated the effect of Reynolds number in the Gruschwitz equation and obtained

$$\frac{-\theta}{U^2} \frac{d(U^2 \eta)}{dx} = 0.00894 \eta - \frac{0.0164}{\log_{10} R_{\theta}} + \frac{0.85}{(R_{\theta} - 300)}$$
 [21]

Using H rather than η as the single parameter for the shape of the velocity profiles, von Doenhoff and Tetervin made an empirical study of the variation of H in pressure gradients in order to obtain an auxiliary equation. From a collection of NACA and other test data representing a range of Reynolds numbers, 1 x 10³ < R, < 7 x 10⁴ roughly, they considered the rate of change of H to vary as follows

$$\theta \frac{dH}{dx} = \left[-2.035(H - 1.286) - \frac{2}{T_{W_0}} \left(\frac{\theta}{U} \frac{dU}{dx} \right) \right] e^{4.680(H - 2.975)}$$
 [22]

where $\tau_{\rm W_a}/\rho {\rm U^2}$ is taken from the flat plate formula of Squire and Young¹¹

$$\frac{\tau_{W_0}}{\rho_{U^2}} = \left[\frac{1}{5.890 \log_{10} (4.075 R_0)}\right]^2$$
 [23]

Von Doenhoff and Tetervin considered separation to occur in the range 1.8 < H < 2.6. It is to be noted that the pressure-gradient parameter is $\frac{\theta}{U} \frac{dU}{dx}$ and the parameter representing the Reynolds-number effect is $\tau_{W_0}/\rho U^2$, the local-skin-friction coefficient. Although these parameters are satisfactory in themselves for describing the flow, their combination into a single term in the empirical equation seems objectionable for analysis.

Using substantially the same data as von Doenhoff and Tetervin and a somewhat different analysis, Garner¹² obtained a more amenable auxiliary equation for the rate of variation of H

$$\theta \frac{dH}{dx} = \left[-\frac{0.0135(H-1.4)}{R_{A}^{1/6}} - \frac{\theta}{U} \frac{dU}{dx} \right] e^{5(H-1.4)}$$
 [24]

The following flat-plate formula of Falkner¹⁵ for the skin-friction-coefficient is used in its determination

$$\frac{\tau_{W_0}}{\rho U^2} = \frac{0.006534}{R_s^{1/6}}$$
 [25]

A noteworthy feature of Garner's equation is the separation of the pressure-gradient parameter $\frac{\theta}{U}\frac{dU}{dx}$ and the Reynolds number R_{\theta} into different terms.

Theoretical derivations of an auxiliary equation have proved very difficult. A strenuous but unsuccessful effort was made by Coleman¹⁴ in 1947. A very promising avenue of approach was introduced, however, more recently by Tetervin and Lin¹⁵ who investigated various integral forms of the Prandtl boundary-layer equation, [1]. By multiplying each term of this equation by an arbitrary function and then integrating, it is possible to derive various families of equations. Using as the multiplying function u^{S1} y^{S2}, where s₁ and s₂ are arbitrary constants, the general integral form of the boundary-layer equation is written

$$\int_0^t u \frac{\partial u}{\partial x} u^{s_1} y^{s_2} dy + \int_0^t v \frac{\partial u}{\partial y} u^{s_1} y^{s_2} dy = -\frac{1}{\rho} \int_0^t \frac{dp}{dx} u^{s_1} y^{s_2} dy + \frac{1}{\rho} \int_0^t \frac{\partial \tau}{\partial y} u^{s_1} y^{s_2} dy$$
 [26]

As before, this equation is accompanied by the equation of continuity, [2]. When both exponents s_1 and s_2 are set equal to zero, the von Kármán momentum equation is specified. When $s_1 = 1$ and $s_2 = 0$, an energy equation results; when $s_1 = 0$ and $s_2 = 1$, a moment-of-momentum equation is indicated.

The moment-of-momentum equation appears to be the most promising of these derived integrated equations for obtaining a theoretical auxiliary equation for the variation of H. Assuming the general-power-law distribution for the velocity profile, [8], Tetervin and Lin obtained the moment-of-momentum equation in the form

$$\theta \frac{dH}{dx} = -\frac{H(H+1)(H^2-1)}{2} \frac{\theta}{U} \frac{dU}{dx} + H(H^2-1) \frac{\tau_W}{\rho U^2} - (H+1)(H^2-1) \int_0^1 \frac{\tau}{\rho U^2} d\left(\frac{y}{\theta}\right)$$
 [27]

This equation is applicable to two-dimensional flows and to axisymmetric flows ($\delta << r_w$). For purposes of calculation it is seen that relations for the variation of the shearing stresses in a pressure gradient are still required. The main objective of this paper is the conversion of the above equation into a usable auxiliary equation by supplying relations for the variation in a pressure gradient of the local-skin-friction coefficient $\tau_w/\rho U^2$ and the integral of the shearing-stress distribution $\int_0^1 \frac{\tau}{\rho U^2} d\left(\frac{y}{\delta}\right)$.

For comparison the various auxiliary equations for the variation of the shape parameter in a pressure gradient are listed in Table 1. It is seen that Buri's method does not provide for an auxiliary equation since no allowance is made for the effect of the previous development of the flow. On the other hand, the Gruschwitz method is correct in utilizing the rate of change of a shape parameter in its analytic formulation. It is seen that Kehl removed one of the main objections to the Gruschwitz method by incorporating the

TABLE 1
Summary of Methods for Calculating the Turbulent Boundary Layer
in a Pressure Gradient

Investigator	Criterion for Separation	Auxiliary Equation (for use with von Kármán Homentum Equation)		Remarks
Buri, 1931 Reference 9	F= -0.06	Hone explicitly; von Kármán momentum equation modific $\frac{d}{dx} \left(R_0^{\frac{1}{4}} \; \theta \; \right) \; = \; a \; - \; b \; f'$	19]	eter for shape of ve- locity profile; no
Gruschwitz, 1931 Reference 5	7 ≥ 0.8	$\frac{-p}{u^0} \frac{d(u^0 \eta)}{dx} = 0.00894 \eta - 0.00461$	[20]	No Reynolds-number effect included; based on test data, 1 x 10 ⁸ < R _s < 4 x 10 ⁸
Kehl, 1943 Reference 6		$-\frac{\theta}{U^{0}}\frac{d(U^{0}\eta)}{dx}=0.00894 \eta-\frac{0.0164}{\log_{10}R_{0}}+\frac{0.85}{(R_{0}-500)}$	[21]	Gruschwitz method ex- tended to include ef- fects of Reynolds num- ber; based on test data 1 x 10° < R, < 3.5 x 10°
von Doenhoff and Tetervin, 1943, Reference 7		$\theta \frac{dH}{dx} = \left[-2.035(H - 1.286) - \frac{2}{T_{op}} \left(\frac{\theta}{V} \frac{dV}{dx} \right) \right] e^{4.000(H - 2.976)}$	[22]	Empirical; based on test data, 1 x 10 ⁸ < R _o < 7 x 10 ⁴
		$\frac{\tau_{M_0}}{\rho U^2} = \left[\frac{1}{5.890 \log_{10}(4.075 R_p)}\right]^2$	[23]	
Gerner, 1944 Reference 12	H = 2.6	$\theta \frac{dH}{dx} = \left[-\frac{0.0135(H-1.4)}{R_{A}^{1/2}} - \frac{\theta}{U} \frac{dU}{dx} \right] e^{i(H-1.4)}$	[24]	Based mostly on same data as von Doenhoff and Tetervin
Tetervin and Lin, 1950, Reference 15		$\theta \stackrel{\text{dif}}{\text{dx}} = \frac{H(H+1)(H^2-1)}{2} \stackrel{\theta}{\text{U}} \stackrel{\text{dif}}{\text{dx}} + H(H^2-1) \frac{T_M}{\rho U^2} - (H+1)(H^2-1) \int_{-\rho U^2}^{1} d\left(\frac{Y}{\delta}\right)$	[27]	Theoretically derived but lacking in shear- ing-stress information required for numerical solution

effects of Reynolds number. Mention is made of an experimental study of the Gruschwitz method by Peters¹⁶ who found that it gave fair results for η but that it seemed useless for predicting separation. The form of the Garner equation is superior to that of the von Doenhoff and Tetervin equations because it separates the pressure-gradient parameter and the Reynolds-number effect. A critical comparison of the two equations just mentioned, made by Fage and Raymer,¹⁷ claimed serious numerical discrepancies between them even though they had both been derived for the most part from the same test data. The moment-of-momentum equation developed in the present report will be found similar in form to that of the Garner equation. A graphical comparison of all the methods with the exception of the Buri method is shown at the end of this report.

LOCAL SKIN FRICTION AS A FUNCTION OF PRESSURE GRADIENT

The manner of the variation of the local skin friction or shearing stress at the wall $\tau_{\rm W}$ with pressure gradient as well as with Reynolds number is required in both the von Kármán momentum equation and the moment-of-momentum equation. Until recently the experimental study of wall shearing stresses was hindered by the poor precision of the existing experimental techniques, based on measuring the rate of change of the momentum and the pressure of the flow through the boundary layer. In 1949 Ludwieg and Tillmann¹⁸ introduced a new method for accurately measuring the wall shearing stress in a pressure gradient. The improved technique, described in Reference 19, consists in measuring the rate of heat transferred to the fluid from a calibrated instrument imbedded in the wall. From their measurements Ludwieg and Tillmann proved that the wall shearing stress diminishes in an adverse pressure gradient, even close to the separation point. In addition, they demonstrated that the so-called "law of the wall" can be used for a quantitative analysis of the variation of the wall shearing stress in a pressure gradient.

The "law of the wall" states that within the boundary layer in a pressure gradient there is a region of flow next to the wall which has velocity and skin-friction characteristics similar to that of a flat plate in a zero pressure gradient. As seen in Figure 7 this region of flow or inner flow has subregions of a laminar sublayer and a transition zone. The Prandtl friction-velocity relationship for a flat plate can then be applied to the whole inner flow or

$$\frac{\mathbf{u}}{\mathbf{u}_{-}} = \mathbf{f}\left(\frac{\mathbf{u}_{\tau}\mathbf{y}}{\nu}\right) \tag{28}$$

where $u_{\tau} = \sqrt{\frac{\tau_W}{\rho}}$ is the friction velocity. The functional relationship satisfying the turbulent portion of the inner flow is

$$\frac{u}{u_r} = C_1 + C_2 \log\left(\frac{u_r y}{\nu}\right)$$
 [29]

For simplicity of analysis, the above logarithmic formulation can be closely approximated by the general power law

$$\frac{u}{u_{\tau}} = c \left(\frac{u_{\tau} y}{\nu}\right)^{n_0} \tag{30}$$

By virtue of the law of the wall, C and n_0 are independent of pressure gradient and depend only on the Reynolds number. The applicability of the power-law formulation is demonstrated in Figure 8 where a logarithmic plot of u/U against y/θ is shown for various pressure gradients. It is seen that the curves are straight and parallel up to about $y=\theta$. This situation can be explained analytically from the power law as follows. Substituting $y=\theta$ and u=u into the power law gives

$$\frac{u_{\theta}}{u_{\tau}} = C \left(\frac{u_{\tau}\theta}{\nu}\right)^{n_0} \tag{31}$$

Dividing Equation [30] by [31] produces

$$\frac{\mathbf{u}}{\mathbf{u}_a} = \left(\frac{\mathbf{y}}{\theta}\right)^{\mathbf{n}_0} \tag{32}$$

or

$$\log \frac{u}{U} = \log \frac{u_{\theta}}{U} + n_{\theta} \log \frac{y}{\theta}$$
 [33]

Since n_0 does not depend on pressure gradient, the curves of log u/U should be straight and parallel up to $y = \theta$.

Ludwieg and Tillmann demonstrated experimentally that the law of the wall is also valid for analyzing the variation of the wall shearing stress in a pressure gradient. From test data in the range of Reynolds number $1 \times 10^3 \leqslant R_{_0} \leqslant 4 \times 10^4$, they obtained the following expression for the variation of the local-skin-friction coefficient in a pressure gradient

$$\frac{\tau_{\rm W}}{\rho U^2} = \frac{0.0290}{R_A^{0.268}} \quad y1.705$$
 [34]

where

$$\gamma = 2.333 \times 10^{-0.398H}$$
 [35]

A general equation for the variation of the skin rriction in a pressure gradient will now be derived from the law of the wall by using the power-law formula for the velocity profile of the inner flow,

$$\frac{\mathbf{u}}{\mathbf{u}_r} = \mathbf{c} \left(\frac{\mathbf{u}_r \mathbf{y}}{\mathbf{v}} \right)^{n_0} \tag{30}$$

As before, at $y = \theta$, $u = u_a$ and

$$\frac{u_{\theta}}{u_{\tau}} = C \left(\frac{u_{\tau}\theta}{\nu}\right)^{n_0}$$
 [31]

After substituting $u_{\tau} = \sqrt{\frac{\tau_W}{\rho}}$ and $\gamma = \frac{u_{\theta}}{U}$, there results

$$\frac{\tau_{W}}{\rho U^{2}} = \left(CR_{\theta}^{n_{0}} \right)^{\frac{2}{1+n_{0}}} \qquad \gamma^{\frac{2}{1+n_{0}}}$$
 [36]

For two different pressure gradients at the same Reynolds number R_{θ} and consequently at the same value of C and n_{θ} , the following ratio can be formed

$$\frac{\left(\frac{\tau_{W}}{\rho U^{2}}\right)_{1}}{\left(\frac{\tau_{W}}{\rho U^{2}}\right)_{2}} = \left(\frac{\gamma_{1}}{\gamma_{2}}\right)^{\frac{2}{1+n_{0}}}$$
 [37]

If the reference condition is that for zero pressure gradient, this equation becomes

$$\frac{\tau_{W}}{\rho U^{2}} = \left(\frac{\tau_{W_{0}}}{\rho U^{2}}\right) \left(\frac{\gamma}{\gamma_{0}}\right)^{\frac{2}{1+\eta_{0}}}$$
 [38]

where the subscript zero refers to zero pressure gradient. For a powerlaw velocity profile of a flat plate with zero pressure gradient, Equation [14] becomes

$$n_0 = \frac{H_0 - 1}{2}$$
 [39]

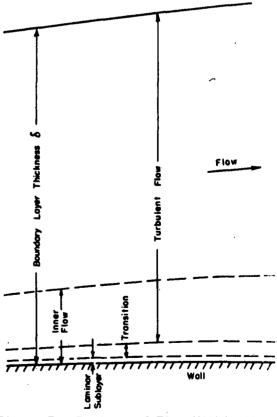


Figure 7 - Regions of Flow Within the Turbulent Boundary Layer in a Pressure Gradient

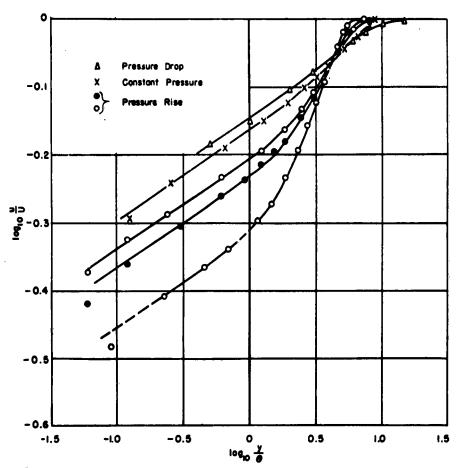


Figure 8 - Logarithmic Plot of Velocity Profiles in Pressure Gradients s Illustrating "The Law of the Wall" (Ludwieg and Tillmann, Reference 18)

Then [38] reduces to
$$\frac{\tau_{\rm W}}{\rho {\rm U}^2} = \frac{\tau_{\rm W_0}}{\rho {\rm U}^2} \left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H_0+1}} \tag{40}$$

Comparing the exponents of γ in [34] and [40], it is seen that the exponent obtained by Ludwieg and Tillmann has a constant value of 1.705 while that of the equation just derived depends on H_0 , which varies with Reynolds number. From Figure 11 showing the variation of H_0 with R_0 , the exponent $\frac{4}{H_0}+1$ is found equal to 1.639 for $R_0=1.5 \times 10^3$, and 1.800 for $R_0=4 \times 10^4$. These values compare favorably with the value 1.705 of Ludwieg and Tillmann.

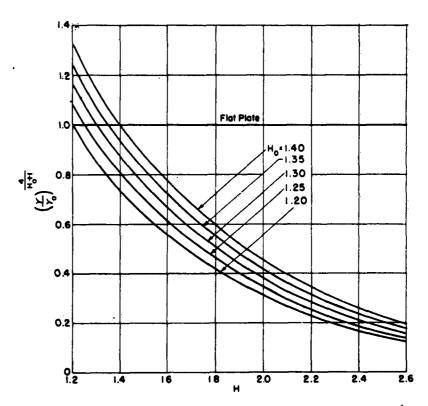


Figure 9 - The Variation of Pressure-Gradient Factor $\left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H_0+1}}$ with H for Different Values of H₀

Since from Equation [9]

$$\gamma = \sqrt{1 - \eta} \tag{41}$$

y may be expressed as a function of H using [15],

$$\gamma = \left[\frac{H-1}{H(H+1)}\right]^{\frac{H-1}{2}} \tag{42}$$

and

$$\gamma_0 = \left[\frac{H_0 - 1}{H_0 (H_0 + 1)} \right]^{\frac{H_0 - 1}{2}}$$
 [43]

The variation of $\left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H_0+1}}$ with H and H₀ is shown in Figure 9. Since this factor which represents the effect of pressure gradient on the skin friction diminishes asymptotically towards zero, with increasing H, it can only describe flow conditions approaching separation and not conditions right at the separation point where the wall shearing stress is zero.

LOCAL-SKIN-FRICTION COEFFICIENTS FOR FLAT PLATES AT ZERO PRESSURE GRADIENT

Since the evaluation of the local skin friction in a pressure gradient depends on a knowledge of its value in zero pressure gradient, as seen in Equation [40], a review of available information on the drag of flat plates should now be considered. A smooth flat plate moving parallel to the direction of motion represents an excellent example of boundary-layer flow in a zero pressure gradient. The analytic study of the drag of flat plates has proceeded on a semi-empirical basis by such investigators as Prandtl and von Kármán.^{1,2} From various theoretical and empirical considerations a functional form is assumed for the velocity profile involving both the velocity and the local skin friction. Then an integration over the length of the plate leads to a general expression for the drag, containing coefficients to be numerically evaluated from test data. Landweber²¹ has made a critical review of such methods.

For the boundary-layer relations considered in this report it is necessary to express the frictional resistance of flat plates in terms of a local-skin-friction coefficient as a function of a local Reynolds number or

$$\frac{\tau_{W_0}}{\rho U^2} = f(R_{\theta}) \tag{44}$$

where $R_{\theta} = \frac{U\theta}{\nu}$. Various investigators have developed expressions of this type from drag coefficient formulas appearing in the literature.

Tetervin²² obtained the following local-skin-friction formula for flat plates from the universal resistance law for pipes

$$\frac{\tau_{W_0}}{\rho U^2} = \left\{ \frac{1}{2.5 \ln \left[\frac{R_0}{2.5 \left(1 - 5 \sqrt{\frac{\tau_{W_0}}{\rho U^2}} \right)} \right] + 5.5} \right\}^2$$
 [45]

Since $\tau_{\rm w}/\rho {\rm U}^2$ appears also on the right hand side, it is an unwieldly equation to use numerically. Furthermore, as it is based on pipe-resistance data, it applies only approximately to flat plates.

Squire and Young¹¹, by a combination of the von Karman asymptotic formula and the Prandtl and Schlichting drag law, derived the following expression for the local-skin-friction coefficient

$$\frac{\tau_{\text{Wo}}}{0.11^2} = \left[\frac{1}{5.890 \log_{10}(4.075 \text{ R}_{\bullet})}\right]^2$$
 [23]

The Prandtl and Schlichting drag law has been criticized for its use of pipe velocity profiles in its derivation.³

Falkner, by a study of various test data for flat plates, proposed the following simple power-law formula

$$\frac{\tau_{W_0}}{\rho U^2} = \frac{0.006534}{R_o^{1/6}}$$
 [25]

Like all power-law formulas, this equation is valid only for a limited range of Reynolds numbers.

Ludwieg and Tillmann¹⁸ derived the following equation from the test data of Schultz-Grunow²³

$$\frac{\tau_{W_0}}{\rho U^2} = \frac{0.0167}{(\log_{10} R_{\bullet})^{1.888}}$$
 [46]

for $2 \times 10^3 < R_a < 7 \times 10^5$.

A local-skin-friction formula will now be derived from the well-known Schoenherr (Kármán-Schoenherr) frictional-resistance formula for flat plates. From an extensive collection of test data for the frictional resistance of flat plates covering a wide range of Reynolds numbers, Schoenherr²⁴ supplied numerical values to the coefficients of the von Kármán asymptotic drag-law formula. The Schoenherr formula has become the basis of frictional-resistance calculations for the prediction of full-scale horsepower from tests on models of ships. The Schoenherr formula is

$$\frac{1}{C_f^{1/2}} = 4.13 \log_{10} (R_{\chi} C_f)$$
 [47]

where $R_{x} = \frac{Ux}{y}$. Here

$$C_{\mathbf{f}} = \frac{D}{\frac{1}{2}\rho U^2 S} \tag{48}$$

where D is the drag and S is the total surface area. Hence for a flat plate of width W and length x the drag of one side is

$$D = C_{f} \frac{1}{2} \rho U^{2} x W \qquad [49]$$

For a flat plate with zero pressure gradient the von Kármán momentum equation reduces to

$$\frac{\mathrm{d}\theta}{\mathrm{dx}} = \frac{\tau_{W_0}}{\rho U^2} \tag{50}$$

or

$$\theta = \frac{1}{\rho U^2} \int_0^x \tau_{W_0} dx$$
 [51]

or

$$\theta = \frac{1}{\rho U^2} \frac{D}{W}$$
 [52]

where by definition

$$\dot{D} = W \int_{0}^{x} \tau_{W_{0}} dx$$

Henc e

$$D = \rho U^2 \theta W$$
 [53]

Finally from Equations [49] and [53]

$$C_{\mathbf{f}} = \frac{2\theta}{\mathbf{x}} \tag{54}$$

The substitution of the relations for C_f from [54] and for R_{χ} into the Schoenherr formula, [47], produces

$$\left(\frac{\theta}{x}\right)^{\frac{1}{2}} = \frac{1}{4.13 \ V2 \ \log_{10}\left(\frac{2U\theta}{y}\right)}$$
 [55]

Differentiation with respect to x gives

$$\frac{d\theta}{dx} = \left(\frac{\theta}{x}\right)^{\frac{1}{2}} \frac{1}{8.26 \sqrt{2}} \left[\frac{1}{\log_{10} \left(\frac{2U\theta}{y}\right)^{\frac{1}{2}} + \log_{10} e} \right]$$
 [56]

Substituting for $\left(\frac{\theta}{x}\right)^{\frac{1}{2}}$ from [55] and using [50] finally results in

$$\frac{\tau_{W_0}}{\rho U^2} = \frac{0.01466}{\log_{10} (2R_a) \left[\frac{1}{2} \log_{10} (2R_a) + 0.4343 \right]}$$
 [57]

With the exception of Falkner's equation, all the local-skin-friction formulas discussed in this section are plotted together in Figure 10 for comparison. It is seen that there are no appreciable numerical differences among them. For convenient reference the flat-plate formulas are listed in Table 2.

TABLE 2
Summary of Formulas for Local-Skin-Friction Coefficients
of Flat Plates

Investigator	Date	Origin	Formula for Local-Skin-Friction Coeff	icient	Remarks
Tetervin Reference 22	1944	Universal Pipe Resistance Law	$\frac{\tau_{M_0}}{\rho U^2} = \left\{ \frac{1}{2.5 \ln \left[\frac{R_0}{2.5 \sqrt{1 + 5\sqrt{\frac{\tau_{M_0}}{\rho U^2}}}} \right] + 5.5} \right\}^{8}$	[45]	Based on pipe resistance data
Squire and Young Reference 11	1937	von Kármán Asymp- totic Formula and Prandtl and Schlichting Drag Law	$\frac{\tau_{W_0}}{\rho U^2} = \left(\frac{1}{5.890 \log_{10} 4.075 R_0}\right)^2$	[23]	
Falkner Reference 13	1943	Experimental Data	$\frac{T_{W_0}}{\rho U^2} = \frac{0.006534}{R_0^{1/6}}$	[25]	Limited range of Reynolds number
Ludwieg and Tillmann Reference 18	1949	Schultz-Grunow Data	$\frac{T_{W_0}}{\rho U^2} = \frac{0.0167}{(\log_{10} R_0)^{1.056}}$	[46]	2 x 10° < R _g < 7 x 10°
Granville (This report)	1951	Schoenherr Formula (von Kármán Asymp- totic Formula)	Two 0.01466 PUT 10g 10 (2R,)[210g 10 (2R,)+0.4343]	[57]	7x-10 ² < R _p < 8x 10 ⁵

In addition to the local-skin-friction coefficient, the variation of the shape parameter of the velocity profiles $\rm H_0$ of flat plates with Reynolds number at zero pressure gradient, is required in Equation [40] to evaluate the local-skin-friction coefficient in a pressure gradient. From the measurements of Schultz-Grunow, ²³ and from unpublished British data, Tetervin and $\rm Lin^{15}$ formulated the following empirical expression

$$\log_{10} H_0 = 0.5990 - 0.1980 \log_{10} R_0 + 0.0189 (\log_{10} R_0)^2$$
 [58]

for 1.5 x 10^3 < R_e < 1 x 10^5 . Figure 11, where Equation [58] is plotted, shows the decrease in H_o with increasing Reynolds number R_e.

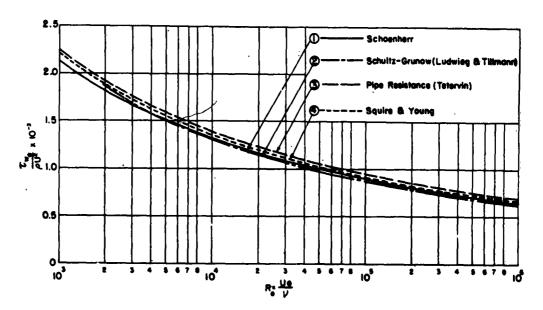


Figure 10 - Local-Skin-Friction Coefficient $\tau_{\rm We}/\rho U^2$ as Function of Local Reynolds Number R, for a Flat Plate

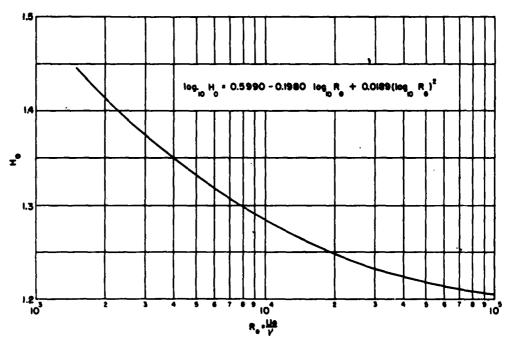


Figure 11 - Variation of Shape Parameter Ho with Local Reynolds Number Ro for Flat Plates (Tetervin and Lin, Reference 15)

INTEGRAL OF THE SHEARING-STRESS DISTRIBUTION ACROSS THE BOUNDARY LAYER

In order for the moment-of-momentum equation [27] to be used numerically a relationship is required which describes the effect of pressure gradients on the integral of the shearing-stress distribution across the boundary layer $\int_0^b \frac{\tau}{\rho U^2} \mathrm{d} \left(\frac{y}{\delta} \right)$. Although almost no study, either theoretical or empirical, has been made of the integral of the shearing-stress distribution, some studies have been made of the shearing-stress distribution itself.

The hot-wire measurements of Schubauer and Klebanoff, 25 shown in Figure 12, demonstrate the large changes produced in the shape of the shearing-stress profile by an adverse pressure gradient. The shearing-stress curves have a positive slope at the wall determined by the positive pressure gradient; they then come to a peak, and finally drop to zero at the outer edge of the boundary layer. Several attempts have been made to derive analytical expressions for the general shearing-stress distribution; these are described below.

Fediaevsky, 26 following the Pohlhausen method for laminar flow, tried to fit a polynomial expression for the shearing-stress distribution that would satisfy the boundary conditions at the inner and outer edges of the boundary layer. The coefficients A_j of the following polynomial are to be evaluated:

$$\frac{\tau}{\tau_{w}} = \sum_{j=0}^{l} A_{j} \left(\frac{y}{\delta}\right)^{j}$$
 [59]

The boundary conditions imposed by Fediaevsky are:

a.	At $y = 0$,	$\frac{\tau}{\tau_{\rm W}} = 1$	by definition,
b.	At $y = 0$,	$\frac{\partial \tau}{\partial y} = \frac{\mathrm{d}p}{\mathrm{d}x}$	from the boundary-layer equation, Equation [1],
. c.	At $y = \delta$,	τ ≈ 0	from the definition of boundary-layer thickness,
d.	At $y = \delta$,	$\frac{\partial \tau}{\partial y} = 0$	from the assumption that the derivative of the total head of the outer streamline is continuous,
٠.	At $y = 0$,	$\frac{\partial^2 \tau}{\partial y^2} = 0$	from the derivative of the boundary-layer equation, Equation [1] and $\partial p/\partial y = 0$.

Substituting only the first three boundary conditions a, b, and c into Equation, [59] and its derivatives to form a system of simultaneous equations for evaluating the coefficients, results in the following quadratic equation for the shearing-stress distribution

$$\frac{\tau}{\tau_{y}} = 1 + \alpha \left(\frac{y}{\delta}\right) - (1 + \alpha) \left(\frac{y}{\delta}\right)^{2}$$
 [60]

where $\alpha = \frac{\delta}{\tau_{\rm w}} \frac{{\rm dp}}{{\rm dx}}$, a pressure-gradient parameter. Using all five boundary conditions yields the following quadratic equation for the shearing-stress distribution

$$\frac{\tau}{\tau_{\mathbf{w}}} = 1 + \alpha \left(\frac{\mathbf{y}}{\delta}\right) - (4 + 3\alpha) \left(\frac{\mathbf{y}}{\delta}\right)^{3} + (3 + 2\alpha) \left(\frac{\mathbf{y}}{\delta}\right)^{4}$$
 [61]

Schubauer and Klebanoff²⁵ found indifferent correlation between their experimental results and either of Fediaevsky's equations. Agreement is good at the

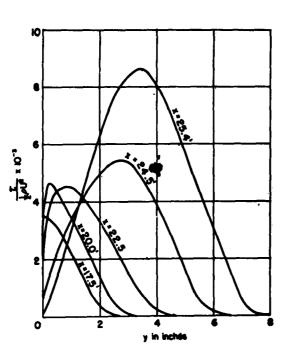


Figure 12 - Shearing-Stress Distributions in an Adverse Pressure Gradient as Measured by Schubauer and Klebanoff, Reference 25, At Various Stations

beginning of the adverse pressure gradient and near the point of separation but is extremely poor at the intermediate stations.

In an attempt to improve on the Fediaevsky formulations, Ross and Robertson²⁷ considered the shearingstress distribution to depend on its previous history of development along the boundary layer. Fediaevsky's boundary condition (d) is altered to $\frac{\partial T}{\partial v} = -\frac{1}{2}$ at y = 4, in order to obtain a constant slope at the outer edge of the boundary layer travelling downstream from 1, the initial position of the adverse pressure gradient. This requirement makes the shearing-stress distribution depend on conditions upstream. Using a modified polynomial expression for τ and incorporating the revised boundary condition (d), together with the other four Fediaevsky conditions. Ross and Robertson derived the following expression:

$$\frac{\tau}{\tau_{W}} = \beta \left(1 - \frac{y}{\delta}\right) - (\alpha + \beta) \left(1 - \frac{y}{\delta}\right)^{q} + (\alpha + 1) \left(1 - \frac{y}{\delta}\right)^{q+1}$$
 [62]

where

$$q = \frac{2\alpha + \beta + 1}{\beta - 1}$$

and

$$\beta = \frac{\tau_{W_i}}{\tau_{W}} \frac{\delta}{\delta_i}$$

A comparison of the above expression with the experimental findings of Schubauer and Klebanoff shows a somewhat better agreement than the Fediaevsky relations.

The integral of the shearing-stress distribution will now be studied by integrating the analytic relations just described for the shearing-stress distribution and by analyzing the test data of Schubauer and Klebanoff. Let

$$I = \int_{0}^{1} \frac{\tau}{\tau_{W}} d\left(\frac{y}{\delta}\right)$$
 [63]

By elementary integration the following expressions are derived: For the Fediaevsky 3-condition polynomial, Equation [60],

$$I = 0.67 + 0.17a$$
 [64]

for the Fediaevaky 5-condition polynomial, Equation [61],

$$I = 0.60 + 0.15\alpha$$
 [65]

and for the Ross and Robertson equation, Equation [62]

$$I = \frac{1}{2} \left(\frac{2\alpha\beta + 5\beta - 3}{2\alpha + 3\beta - 1} \right)$$
 [66]

Significant results are obtained from the data of Schubauer and Klebanoff when the integral of the shearing-stress distribution is non-dimensionalized as follows

$$\psi = \int_0^{\delta/\delta^2} \frac{\tau}{\rho U^2} d\left(\frac{y}{\delta^2}\right)$$
 [67]

0r

$$\psi = \left(\frac{\tau_{\infty}}{2}\right)\left(\frac{A}{2}\right) \mathbf{I} \tag{68}$$

Values of ψ are computed directly from the measurements of Schubauer and Klebanoff by substituting data into Equation [67] and performing the indicated integrations numerically by Simpson's rule. For comparison, values of ψ are obtained from the analytical formulations of I based on the methods of Fediaevsky and of Ross and Robertson by inserting values of α and β from the experimental data into Equations [64], [65], and [66]. As seen in Figure 13, in which ψ is plotted for various stations along the boundary layer, both of the Fediaevsky formulations show poor correlation with experimental points while the Ross and Robertson formulation shows only fair agreement. It is observed that except for experimental error the value of ψ is practically constant for different stations along the boundary layer. This suggests that using a value of ψ independent of the effects of pressure gradient ought to be sufficiently accurate for most technical problems encountered.

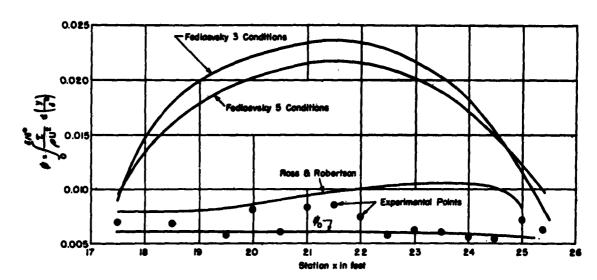


Figure 13 - Integral of Shearing Stresses Across the Boundary Layer for Data of Schubauer and Klebanoff, Reference 25

Before deciding on values of ψ for pressure gradients in general, it will prove fruitful to investigate the values of ψ in a zero pressure gradient. From Equation [68] ψ for a zero pressure gradient or ψ_0 may be written as

$$\psi_0 = \frac{\tau_{W_0}}{\rho U^2} \frac{\theta_0}{\theta_0^*} I_0 \tag{69}$$

From [12], where a power law for the velocity profile is assumed,

$$\frac{\delta_0}{\delta_0^0} = \frac{H_0 + 1}{H_0 - 1}$$
 [70]

Then

$$\psi_{0} = \left(\frac{\tau_{W_{0}}}{\rho U^{2}}\right) \left(\frac{H_{0}+1}{H_{0}-1}\right) I_{0}$$
 [71]

The value of I_0 is now derived analytically from the momentum and from the moment-of-momentum equations for flat plates with zero pressure gradient $\left(\frac{dU}{dx}=0\right)$ in the following manner. The moment-of-momentum equation, [27], reduces to

$$\theta \frac{dH_0}{dx} = (H_0^2 - 1) \left[H_0 - (H_0 + 1) I_0 \right] \frac{\tau_{W_0}}{\rho U^2}$$
 [72]

and the momentum equation to

$$\frac{\mathrm{d}\theta}{\mathrm{d}x} = \frac{\tau_{\mathrm{W_0}}}{\rho \mathrm{U}^2} \tag{50}$$

Combining both equations gives

$$\theta \frac{dH_0}{dx} = (H_0^2 - 1) \left[H_0 - (H_0 + 1) I_0 \right] \frac{d\theta}{dx}$$
 [73]

or

$$\frac{dH_0}{d\theta} = \frac{(H_0^2 - 1)[H_0 - (H_0 + 1)]}{\theta}$$
 [74]

In terms of $R_{\theta} = \frac{U\theta}{\nu}$, [74] becomes

$$\frac{dH_0}{dR_0} = \frac{(H_0^2 - 1) \left[H_0 - (H_0 + 1) I_0 \right]}{R_0}$$
 [75]

Differentiation of the empirical equation of H_0 , Equation [58], with respect to R_0 produces

$$\frac{dH_0}{dR_0} = \frac{(-0.1980 + 0.0378 \log_{10} R_0) H_0}{R_0}$$
 [76]

Finally I_0 is evaluated by equating [75] and [76]. Then

$$I_0 = \frac{H_0}{H_0 + 1} \left[1 + \frac{0.1980 - 0.0378 \log_{10} R_0}{H_0^2 - 1} \right]$$
 [77]

 R_{\bullet} may be eliminated by use of Equation [58] to give

$$I_0 = \frac{H_0}{H_0 + 1} \left[1 + \frac{0.0378 \sqrt{52.9 \log_{10} H_0 - 4.18}}{H_0^2 - 1} \right]$$
 [78]

The small variation of I_0 with Reynolds number R_0 is shown in Figure 14. For instance, at $R_0=1500$, $I_0=0.633$ and at $R_0=100,000$, $I_0=0.554$. These values appear reasonable when compared with those based on the Fediaevsky formulations: From Equation [64] for three conditions $I_0=0.67$ ($\alpha=0$ for zero pressure gradient) and from Equation [65] for five conditions $I_0=0.60$.

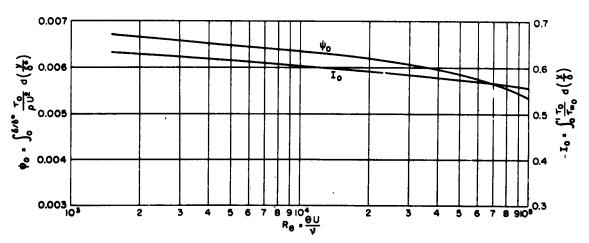


Figure 14 - Variation of Integral of Shearing Stresses across Boundary Layer with Reynolds Number R. for Flat Plates

Finally from Equations [71] and [78], ψ_0 is written

$$\psi_{0} = \left(\frac{\tau_{W_{0}}}{\rho U^{2}}\right)\left(\frac{H_{0}}{H_{0}-1}\right)\left[1 + \frac{0.0378\sqrt{52.9 \log_{10} H_{0}-4.18}}{H_{0}^{2}-1}\right]$$
 [79]

Using the value of $\tau_{\rm W_0}/\rho \rm U^2$ from [57], derived from the Schoenherr formula, and the value of H₀ from [58], the variation of $\psi_{\rm e}$ with Reynolds number is shown graphically in Figure 14. It is seen that $\psi_{\rm e}$ diminishes gradually with Reynolds number.

When the values of ψ_0 , based on the same Reynolds number as those appearing in the experiments of Schubauer and Klebanoff, are plotted in Figure 13 for comparison, they produce a curve of almost constant value which is in excellent agreement with the experimental points of ψ . Based on this evidence it will be reasonable to conclude that at the same Reynolds number ψ_0 is a close approximation to ψ for other boundary layers in pressure gradients similar to the boundary layer of Schubauer and Klebanoff. Further substantiation depends on additional experimentation, especially at high Reynolds numbers.

The integral of the shearing-stress distribution as required by the moment-of-momentum equation, Equation [27], is expressed in terms of ψ as follows:

$$\int_{0}^{1} \frac{\tau}{\rho U^{2}} d\left(\frac{y}{\delta}\right) = \frac{\delta^{*}}{\delta} \int_{0}^{\delta/\delta^{*}} \frac{\tau}{\rho U^{2}} d\left(\frac{y}{\delta}\right) = \frac{\delta^{*}}{\delta} \psi$$
 [80]

For power-law velocity profiles

$$\frac{d^*}{d} = \frac{H-1}{H+1}$$
 [12]

and with the assumption $\psi = \psi_0$, where ψ_0 is defined in Equation [71], the integral of the shearing-stress distribution finally becomes

$$\int_{0}^{1} \frac{\tau}{\rho \mathbf{U}^{2}} d\left(\frac{\mathbf{y}}{\delta}\right) = \left(\frac{\mathbf{H} - 1}{\mathbf{H} + 1}\right) \left(\frac{\mathbf{H}_{0} + 1}{\mathbf{H}_{0} - 1}\right) \left(\frac{\tau_{\mathbf{W}_{0}}}{\rho \mathbf{U}^{2}}\right) \mathbf{I}_{0}$$
 [81]

This completes the shearing-stress relations required for transforming the moment-of-momentum equation into an auxiliary equation for characterizing the shape of the velocity profiles.

MODIFIED MOMENTUM AND MOMENT-OF-MOMENTUM EQUATIONS

The substitution of the relation for local skin friction in a pressure gradient, Equation [40], into the von Karman momentum equations, [6a] and [6b], modifies them as follows: For two-dimensional flows,

$$\frac{d\theta}{dx} = -(H + 2) \frac{\theta}{U} \frac{dU}{dx} + \left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H+1}} \frac{\tau_{W_0}}{\rho U^2}$$
 [82a]

and for axisymmetric flows (where $\delta \ll r_{_{\mathrm{W}}}$),

$$\frac{d(\mathbf{r}_{\mathbf{W}}\theta)}{d\mathbf{x}} = -(\mathbf{H} + 2) \frac{\mathbf{r}_{\mathbf{W}}\theta}{\mathbf{U}} \frac{d\mathbf{U}}{d\mathbf{x}} + \left(\frac{\gamma}{\gamma_{\theta}}\right)^{\frac{4}{H_{\theta}+1}} \mathbf{r}_{\mathbf{W}} \frac{\tau_{\mathbf{W}_{\theta}}}{e^{\mathbf{U}^{2}}}$$
[82b]

The insertion of the relations for local skin friction and for the integral of the shearing-stress distribution, [40] and [81], into the moment-of-momentum equation [27], converts it into the following equation, which is applicable to the calculation of both two-dimensional and axisymmetric flows where $\delta \ll r_{\rm w}$)

$$\theta \frac{dH}{dx} = -\frac{H(H+1)(H^2-1)}{2} \frac{\theta}{U} \frac{dU}{dx} + (H^2-1) \left[H\left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H_0+1}} - (H-1) \frac{(H_0+1)}{(H_0-1)} I_0 \right] \frac{\tau_{W_0}}{\rho U^2}$$
 [83]

where γ , γ_0 and I_0 are defined in Equations [42], [43], and [78] respectively, and the subscript $_0$ refers to flat-plate values at the same Reynolds number R_0 . This equation is the desired auxiliary equation to be solved simultaneously with one of the modified von Kármán momentum equations, [82a] or [82b], for calculating the growth of boundary layers in pressure gradients.

The modified moment-of-momentum equation of this report represents an auxiliary equation whose form has a theoretical basis and whose coefficients have been evaluated indirectly from flat-plate data. On the other hand the various auxiliary equations described in this report are almost wholly empirical in origin. A comparison of the auxiliary equations may be made by writing them in the following generalized form

$$\theta \frac{dH}{dx} = -A \left(\frac{\theta}{U} \frac{dU}{dx} \right) - B$$
 [84]

The expression for the variation of η in the Gruschwitz or Kehl method is converted into the above form by using the power-law formula, [15], for the relation between η and H. The expressions for the coefficients, A and B, are listed in Table 3 for the various auxiliary equations. It is seen that the coefficients for the Kehl, Garner and the moment-of-momentum equations are functionally similar with A = f(H) and B = $f(H, R_{\theta})$. The von Doenhoff and Tetervin equation, nowever, has the Reynolds-number effect in coefficient A instead of coefficient B. As expected, none of the coefficients for the Gruschwitz method exhibits a Reynolds-number effect.

The coefficients A and B are plotted against H in Figures 15, 16, and 17 for two different values of R. It is observed that although all the curves have the same general shape and trend, there are marked differences in the magnitude of the ordinates. The exponential form of the coefficients of the Garner and of the von Doenhoff and Tetervin equations is responsible for the very large increase in value of the coefficients at the higher values of H. The curves for the coefficients of the modified moment-of-momentum equation of this report maintain average positions among the other curves.

TABLE 3

Summary of Coefficients of General Auxillary Equation for Various Formulations

	General Auxiliary	General Auxiliary Equation, $\theta \frac{dH}{dx} = -A \left(\frac{\theta}{U} \frac{dU}{dx} \right) - B$
Equation	V	В
Gruschwitz Equation [20]	where	$\frac{1}{E_{\gamma}^2}(0.00433 - 0.00894\gamma^2)$
	$E = \frac{H^2 - 2H - 1}{H^2 + H} - \frac{2.301}{H - 1} \log_{10} \gamma^2$	$\gamma^2 = \left[\frac{H-1}{H(H+1)} \right]^H - 1$
Kehl Equation [21]	Same	$\frac{1}{E\gamma^2} \left[0.00894(1-\gamma^2) - \frac{0.0164}{10g_{10}R_{\theta}} + \frac{0.85}{(R_{\theta}-300)} \right]$
von Doenhoff and Tetervin Equation [22]	2(5.890 log ₁₀ 4.075 R _g) ² e ^{4.680(н - 2.975)}	2.035(Н - 1.286)е 4.680(н - 2.975)
Garner Equation [24]	9 5(H - 1.4)	$\frac{0.0135(H-1.4)}{R_{\bullet}^{1/6}} e^{5(H-1.4)}$
Moment-of- Momentum Equation [83]	$\frac{H(H+1)(H^2-1)}{2}$	$(H^{2}-1) \left[(H-1) \frac{(H_{0}+1)}{(H_{0}-1)} I_{0} - H \left(\frac{\gamma}{\gamma_{0}} \right)^{\overline{H_{0}}+1} \right]^{T_{W_{0}}} $

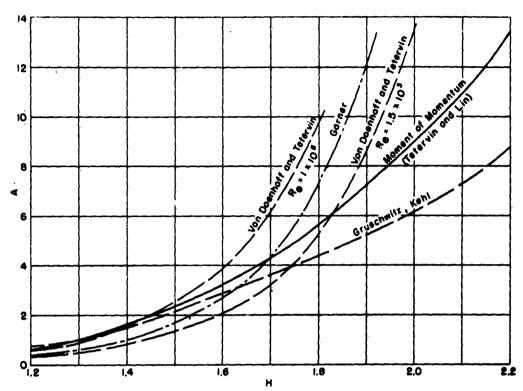


Figure 15 - Coefficient A of General Auxiliary Equation Compared for Various Formulations

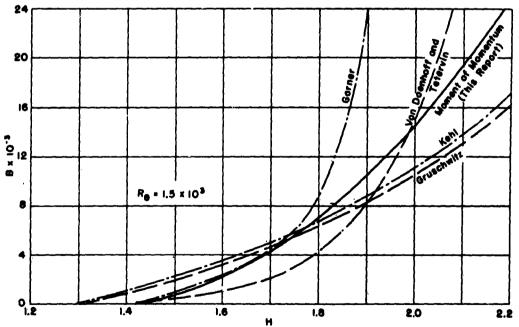


Figure 16 - Coefficient B of General Auxiliary Equation Compared for Various Formulations at Reynolds Number R_{\bullet} = 1.5 x 10

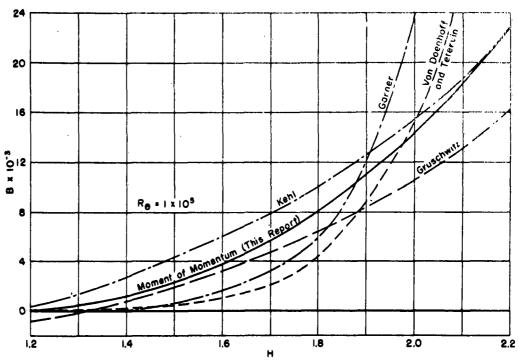


Figure 17 - Coefficient B of General Auxiliary Equation Compared for Various Formulations at Reynolds Number $R_{\theta}=1 \times 10^5$

Although this fact does not conclusively prove the validity of the modified moment-of-momentum equation, it does indicate that—as such—the modified moment-of-momentum equation has a proper range of values for an auxiliary equation giving the variation of H. There is a need for a larger body of reliable measurements of turbulent boundary layers under a variety of conditions and for increased emphasis on measurements of the shearing stresses both at the surface and throughout the boundary layer.

SUMMARY OF METHOD OF CALCULATING TURBULENT BOUNDARY LAYERS IN A PRESSURE GRADIENT

For calculating turbulent boundary layers in a pressure gradient the following relations are involved: The momentum equation for two-dimensional flows,

$$\frac{d\theta}{dx} = -(H + 2) \frac{\theta}{U} \frac{dU}{dx} + \left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H_0+1}} \frac{\tau_{W_0}}{\rho U^2}$$
 [82a]

or the momentum equation for axisymmetric flow ($\delta << r_{_{M}}$),

$$\frac{d(\mathbf{r}_{\mathbf{W}}\theta)}{d\mathbf{x}} = -(\mathbf{H} + 2) \frac{\mathbf{r}_{\mathbf{W}}\theta}{\mathbf{U}} \frac{d\mathbf{U}}{d\mathbf{x}} + \left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H_0+1}} \mathbf{r}_{\mathbf{W}} \frac{\tau_{\mathbf{W}_0}}{\rho \mathbf{U}^2}$$
 [82b]

and the moment-of-momentum equation which holds for both two-dimensional and axisymmetric flows ($\delta << r_w$),

$$\theta \frac{dH}{dx} = -\frac{H(H+1)(H^2-1)}{2} \frac{\theta}{U} \frac{dU}{dx} + (H^2-1) \left[H\left(\frac{\gamma}{\gamma_0}\right)^{\frac{4}{H_0+1}} - (H-1) \frac{(H_0+1)}{(H_0-1)} I_0 \right] \frac{\tau_{W_0}}{\theta U^2}$$
 [83]

where

$$\gamma = \left[\frac{H-1}{H(H+1)}\right]^{\frac{H-1}{2}} \tag{42}$$

and

$$\gamma_0 = \left[\frac{H_0 - 1}{H_0 (H_0 + 1)} \right]^{\frac{H_0 - 1}{2}}$$
 [43]

The variation of $(\gamma/\gamma_0)^{\frac{4}{H_0+1}}$ with H and H₀ is shown in Figure 9. The variation of H₀ with R_a, shown in Figure 11, is given by Reference 15 as

$$\log_{10} H_0 = 0.5990 - 0.1980 \log_{10} R_0 + 0.0189(\log_{10} R_0)^2$$
 [58]

The relation between I and H is

$$I_{0} = \frac{H_{0}}{H_{0}+1} \left[1 + \frac{0.0378 \sqrt{52.9 \log_{10} H_{0}-4.18}}{H_{0}^{2}-1} \right]$$
 [78]

Figure 14 shows I_0 as a function of R_0 . The variation of $\frac{T_0}{W_0}/\rho U^2$ with R_0 , Figure 10, for the Schoenherr formula is

$$\frac{\tau_{W_0}}{\rho U^2} = \frac{0.01466}{\log_{10} (2R_{\bullet}) \left[\frac{1}{2} \log_{10} (2R_{\bullet}) + 0.4343\right]}$$
 [57]

The variation of U and dU/dx with x will be specified for a particular problem and may be obtained either by pressure measurements or potential-flow calculations.

The momentum and moment-of-momentum equations are solved for $\theta(x)$ and H(x) as a pair of simultaneous differential equations, usually by numerical methods involving step-wise integration. The initial conditions for $\theta(x)$ and H(x) are imposed by the physical conditions of the problem such as the

transition point from laminar to turbulent flow. It is customary to use the value of θ of the laminar boundary layer at the transition point as the initial value of θ for the turbulent boundary layer. Owing to the lack of reliable data on transition, the initial value of H may be taken as that for a flat plate at the same Reynolds number R_{\bullet} .

The evaluation of θ and H is required in many technical hydrodynamic and aerodynamic applications involving calculations of drag and of velocity profiles of boundary layers. According to the following formula of Squire and Young¹¹ for the profile drag of airfoils, θ and H must be determined at the trailing edge

 $D = \rho U_{\infty}^2 \theta_t \left(\frac{U_t}{U_{\infty}}\right)^{\frac{H_t + 5}{2}}$ [85]

where the subscript t refers to conditions at the trailing edge. If a power-law distribution is assumed, the values of θ and H at any station along the boundary layer specify the shape and thickness of the velocity profile, as shown by Equation [16],

$$\frac{u}{u} = \left[\left(\frac{y}{\theta} \right) \frac{(H-1)}{H(H+1)} \right]^{\frac{H-1}{2}}$$
 [16]

A knowledge of the characteristics of the velocity profiles of boundary layers is required for the design of control surfaces and propellers on forms moving in fluids and of the various conduit sections of water and wind tunnels. Large values of H indicate the danger of flow separation for cases involving adverse pressure gradients.

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- Directeur du Bassin d'Essais Des Carènes, 6, Boulevard Victor, Paris XV, France
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- Editor, Journal of the British Shipbuilding Research Association, 5, Chesterfield Gardens, Curzon St., London W. 1, England
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- Editor, Index Aeronauticus, Ministry of Supply, Millbank, London S.W. 1, England
- Head, Aerodynamics Department, Royal Aircraft Establishment, Farnborough, Hants, England
- Head, Aerodynamics Division, National Physical Laboratory, Teddington, Middlesex, England
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- Dr. R. Timman, National Luchtvaartlaboratorium, Sloterwag 145, Amsterdam, The Netherlands
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